Fields

Functions

void void

float

Return Type

iPhysicsWorld

iPhysicsWorld has no public fields.

Function Name

PostUpdate

SetMaxTimeStep

GetMaxTimeStep

iPhysicsJointBall@	CreateJointBall	const cVector3f ∈ avPivotPoint, const cVector3f ∈ avPinDir, iPhysicsBody@ apParentBody,
void	DestroyShape	iCollideShape@ apShape const tString& asName,
iCollideShape@	CreateCompundShape	avShapes
void	SaveMeshShapeToBuffer	iCollideShape@ apMeshShape, cBinaryBuffer@ apBuffer
iCollideShape@	LoadMeshShapeFromBuffer	cBinaryBuffer@ apBuffer
iCollideShape@	CreateMeshShape	iVertexBuffer@ apVtxBuffer
iCollideShape@	CreateCapsuleShape	float afRadius, float afHeight, cMatrixf ∈ a_mtxOffsetMtx
iCollideShape@	CreateCylinderShape	float afRadius, float afHeight, cMatrixf ∈ a_mtxOffsetMtx
iCollideShape@	CreateSphereShape	const cVector3f& avRadii, cMatrixf ∈ a_mtxOffsetMtx
iCollideShape@	CreateBoxShape	const cVector3f& avSize, cMatrixf ∈ a_mtxOffsetMtx
int	GetNumberOfThreads	
void	SetNumberOfThreads	int alThreads
iCharacterBody@	GetCharacterBodyFromID	tID aID
iPhysicsJoint@	GetPhysicsJointFromID	tID aID
iPhysicsBody@	GetPhysicsBodyFromID	tID aID
ePhysicsAccuracy	GetAccuracyLevel	
void	SetAccuracyLevel	ePhysicsAccuracy aAccuracy
cVector3f	GetGravity	
void	SetGravity	const cVector3f ∈ avGravity
cVector3f	GetWorldSizeMax	
cVector3f	GetWorldSizeMin	
void	SetWorldSize	const cVector3f& avMin, const cVector3f& avMax

Description

float afTimeStep

float afTimeStep

Parameters

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Return Type	Function Name	Parameters	Description
iPhysicsJointHinge@	CreateJointHinge	const tString& asName, const cVector3f ∈ avPivotPoint, const cVector3f ∈ avPinDir, iPhysicsBody@ apParentBody, iPhysicsBody@ apChildBody	
iPhysicsJointSlider@	CreateJointSlider	const tString& asName, const cVector3f ∈ avPivotPoint, const cVector3f ∈ avPinDir, iPhysicsBody@ apParentBody, iPhysicsBody@ apChildBody	
tID	CreateJointBallID	const tString& asName, const cVector3f ∈ avPivotPoint, const cVector3f ∈ avPinDir, iPhysicsBody@ apParentBody, iPhysicsBody@ apChildBody	
tID	CreateJointHingeID	const tString& asName, const cVector3f ∈ avPivotPoint, const cVector3f ∈ avPinDir, iPhysicsBody@ apParentBody, iPhysicsBody@ apChildBody	
tID	CreateJointSliderID	const tString& asName, const cVector3f ∈ avPivotPoint, const cVector3f ∈ avPinDir, iPhysicsBody@ apParentBody, iPhysicsBody@ apChildBody	
void	DestroyJoint	iPhysicsJoint@ apJoint	
iPhysicsJoint@	GetJoint	const tString& asName	
bool	JointExists	iPhysicsJoint@ apJoint	
iPhysicsMaterial@	CreateMaterial	const tString& asName	
iPhysicsMaterial@	GetMaterialFromName	const tString& asName	
iPhysicsMaterial@	GetMaterialFromId	int alld	
iPhysicsBody@	CreateBody	const tString& asName, iCollideShape@ apShape, float afMass	
tID	CreateBodyID	const tString& asName, iCollideShape@ apShape, float afMass	
void	DestroyBody	iPhysicsBody@ apBody	
iPhysicsBody@	GetBody	const tString& asName	
iCharacterBody@	CreateCharacterBody	const tString& asName, const cVector3f& avSize	
tID	CreateCharacterBodyID	const tString& asName, const cVector3f& avSize	
void	DestroyCharacterBody	iCharacterBody@ apBody	
iPhysicsBody@	GetCharacterBody	const tString& asName	
void	GetBodiesInAABB	const cVector3f ∈ avMin, const cVector3f ∈ avMax, apBodyVec	

Return Type	Function Name	Parameters	Description
void	EnableBodiesInAABB	const cVector3f ∈ avMin, const cVector3f ∈ avMax, bool abEnabled	
iPhysicsRope@	CreateRope	const tString& asName, const cVector3f& avStartPos, const cVector3f& avEndPos	
iPhysicsRope@	GetRope	const tString& asName	
iPhysicsRope@	GetRopeFromUniqueID	int allD	
void	DestroyRope	iPhysicsRope@ apRope	
iPhysicsCloth@	CreateCloth	const tString& asName, const cVector3f& avStartPos, const cVector2f& avClothSize, int alDimension	
iPhysicsCloth@	GetCloth	const tString& asName	
iPhysicsCloth@	GetClothFromUniqueID	int allD	
void	DestroyCloth	iPhysicsCloth@ apCloth	
iPhysicsController@	CreateController	const tString& asName	
void	DestroyController	iPhysicsController@ apController	
void	FadeoutAllLoopSounds	float afFadeSpeed	
bool	CheckShapeCollision	iCollideShape@ apShapeA, const cMatrixf ∈ a_mtxA, iCollideShape@ apShapeB, const cMatrixf ∈ a_mtxB, cCollideData& aCollideData, int alMaxPoints, bool abCorrectNormalDirection, <i>int alThreadID</i> = 0	
float	CastRayOnShape	iCollideShape@ apShape, const cMatrixf ∈ a_mtxTransform, const cVector3f& avOrigin, const cVector3f ∈ avEnd, cVector3f &out avOutNormal, bool abLocalRayPositions	
bool	CheckShapeWorldCollision	cVector3f &out avPushVector, iCollideShape@ apShape, const cMatrixf ∈ a_mtxTransform, iPhysicsBody@ apSkipBody, bool abSkipStatic, bool abIsCharacter, bool abCollideCharacter	
bool	CheckShapeWorldCollision	cVector3f &out avPushVector, iCollideShape@ apShape, const cMatrixf ∈ a_mtxTransform, iPhysicsBody@ apSkipBody, bool abSkipStatic	
void	RenderShapeDebugGeometry	iCollideShape@ apShape, const cMatrixf ∈ a_mtxTransform, iLowLevelGraphics@ apLowLevel, const cColor ∈ aColor	
void	RenderDebugGeometry	iLowLevelGraphics@ apLowLevel	

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Remarks

Have some helpful descriptions to add to this class? Edit this page and add your insight to the Wiki!

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